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# COMPLEX NUMBER

## 1. The complex number system

$z = a + ib$ , then  $a - ib$  is called conjugate of  $z$  and is denoted by  $\bar{z}$ .

## 2. Equality In Complex Number:

$$z_1 = z_2 \Rightarrow \operatorname{Re}(z_1) = \operatorname{Re}(z_2) \text{ and } \operatorname{Im}(z_1) = \operatorname{Im}(z_2).$$

## 3. Properties of arguments

- (i)  $\arg(z_1 z_2) = \arg(z_1) + \arg(z_2) + 2m\pi$  for some integer  $m$ .
- (ii)  $\arg(z_1/z_2) = \arg(z_1) - \arg(z_2) + 2m\pi$  for some integer  $m$ .
- (iii)  $\arg(z^2) = 2\arg(z) + 2m\pi$  for some integer  $m$ .
- (iv)  $\arg(z) = 0 \Leftrightarrow z$  is a positive real number
- (v)  $\arg(z) = \pm \pi/2 \Leftrightarrow z$  is purely imaginary and  $z \neq 0$

## 4. Properties of conjugate

$$(i) \quad |z| = |\bar{z}| \quad (ii) \quad z\bar{z} = |z|^2 \quad (iii) \quad \overline{z_1 + z_2} = \bar{z}_1 + \bar{z}_2$$

$$(iv) \quad \overline{z_1 - z_2} = \bar{z}_1 - \bar{z}_2 \quad (v) \quad \overline{z_1 z_2} = \bar{z}_1 \bar{z}_2$$

$$(vi) \quad \overline{\left(\frac{z_1}{z_2}\right)} = \frac{\bar{z}_1}{\bar{z}_2} \quad (z_2 \neq 0)$$

$$(vii) \quad |z_1 + z_2|^2 = (z_1 + z_2) \overline{(z_1 + z_2)} = |z_1|^2 + |z_2|^2 + z_1 \bar{z}_2 + \bar{z}_1 z_2$$

$$(viii) \quad \overline{(\bar{z}_1)} = z \quad (ix) \quad \text{If } w = f(z), \text{ then } \bar{w} = f(\bar{z})$$

$$(x) \quad \arg(z) + \arg(\bar{z})$$

## 5. Rotation theorem

If  $P(z_1)$ ,  $Q(z_2)$  and  $R(z_3)$  are three complex numbers and  $\angle PQR = \theta$ , then

$$\left(\frac{z_3 - z_2}{z_1 - z_2}\right) = \left|\frac{z_3 - z_2}{z_1 - z_2}\right| e^{i\theta}$$

## 6. Demoivre's Theorem :

If  $n$  is any integer then

- (i)  $(\cos \theta + i \sin \theta)^n = \cos n\theta + i \sin n\theta$
- (ii)  $(\cos \theta_1 + i \sin \theta_1) (\cos \theta_2 + i \sin \theta_2) (\cos \theta_3 + i \sin \theta_3) \dots (\cos \theta_n + i \sin \theta_n) = \cos(\theta_1 + \theta_2 + \theta_3 + \dots + \theta_n) + i \sin(\theta_1 + \theta_2 + \theta_3 + \dots + \theta_n)$

## 7. Cube Root Of Unity :

- (i) The cube roots of unity are  $1, \frac{-1 + i\sqrt{3}}{2}, \frac{-1 - i\sqrt{3}}{2}$ .
- (ii) If  $\omega$  is one of the imaginary cube roots of unity then  $1 + \omega + \omega^2 = 0$ .  
In general  $1 + \omega^r + \omega^{2r} = 0$ ; where  $r \in \mathbb{I}$  but is not the multiple of 3.

## 8. Geometrical Properties:

**Distance formula :**  $|z_1 - z_2|$ .

**Section formula :**  $z = \frac{mz_2 + nz_1}{m+n}$  (internal division),  $z = \frac{mz_2 - nz_1}{m-n}$  (external division)

- (1)  $\arg(z) = \theta$  is a ray emanating from the origin inclined at an angle  $\theta$  to the x-axis.
- (2)  $|z - a| = |z - b|$  is the perpendicular bisector of the line joining a to b.
- (3) If  $\left| \frac{z - z_1}{z - z_2} \right| = k \neq 1, 0$ , then locus of  $z$  is circle.

# VECTORS

## I. Position Vector Of A Point:

let O be a fixed origin, then the position vector of a point P is the vector

$\vec{OP}$ . If  $\vec{a}$  and  $\vec{b}$  are position vectors of two points A and B, then,

$$\vec{AB} = \vec{b} - \vec{a} = \text{pv of B} - \text{pv of A}.$$

**DISTANCE FORMULA :** Distance between the two points A ( $\vec{a}$ ) and B ( $\vec{b}$ )

$$\text{is } AB = \left| \vec{a} - \vec{b} \right|$$

**SECTION FORMULA :**  $\vec{r} = \frac{n\vec{a} + m\vec{b}}{m+n}$ . Mid point of AB =  $\frac{\vec{a} + \vec{b}}{2}$ .

**II. Scalar Product Of Two Vectors:**  $\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos \theta$ , where  $|\vec{a}|$ ,  $|\vec{b}|$  are magnitude of  $\vec{a}$  and  $\vec{b}$  respectively and  $\theta$  is angle between  $\vec{a}$  and  $\vec{b}$ .

1.  $\hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = 1$ ;  $\hat{i} \cdot \hat{j} = \hat{j} \cdot \hat{k} = \hat{k} \cdot \hat{i} = 0$       projection of  $\vec{a}$  on  $\vec{b} = \frac{\vec{a} \cdot \vec{b}}{|\vec{b}|}$

2. If  $\vec{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$  &  $\vec{b} = b_1\hat{i} + b_2\hat{j} + b_3\hat{k}$  then  $\vec{a} \cdot \vec{b} = a_1b_1 + a_2b_2 + a_3b_3$

3. The angle  $\phi$  between  $\vec{a}$  &  $\vec{b}$  is given by  $\cos \phi = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}| |\vec{b}|}$ ,  $0 \leq \phi \leq \pi$

4.  $\vec{a} \cdot \vec{b} = 0 \Leftrightarrow \vec{a} \perp \vec{b}$  ( $\vec{a} \neq 0$   $\vec{b} \neq 0$ )

**III. Vector Product Of Two Vectors:**

1. If  $\vec{a}$  &  $\vec{b}$  are two vectors &  $\theta$  is the angle between them then  $\vec{a} \times \vec{b} = |\vec{a}| |\vec{b}| \sin \theta \vec{n}$ , where  $\vec{n}$  is the unit vector perpendicular to both  $\vec{a}$  &  $\vec{b}$  such that  $\vec{a}, \vec{b}$  &  $\vec{n}$  forms a right handed screw system.

2. Geometrically  $|\vec{a} \times \vec{b}|$  = area of the parallelogram whose two adjacent sides are represented by  $\vec{a}$  &  $\vec{b}$ .

3.  $\hat{i} \times \hat{i} = \hat{j} \times \hat{j} = \hat{k} \times \hat{k} = \vec{0}$ ;  $\hat{i} \times \hat{j} = \hat{k}$ ,  $\hat{j} \times \hat{k} = \hat{i}$ ,  $\hat{k} \times \hat{i} = \hat{j}$

4. If  $\vec{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$  &  $\vec{b} = b_1\hat{i} + b_2\hat{j} + b_3\hat{k}$  then

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

5.  $\vec{a} \times \vec{b} = \vec{0} \Leftrightarrow \vec{a}$  and  $\vec{b}$  are parallel (collinear)

( $\vec{a} \neq 0, \vec{b} \neq 0$ ) i.e.  $\vec{a} = K\vec{b}$ , where K is a scalar.

6. Unit vector perpendicular to the plane of  $\vec{a}$  &  $\vec{b}$  is  $\hat{n} = \pm \frac{\vec{a} \times \vec{b}}{|\vec{a} \times \vec{b}|}$

☞ If  $\vec{a}, \vec{b}$  &  $\vec{c}$  are the pv's of 3 points A, B & C then the vector area of triangle

$$ABC = \frac{1}{2} [\vec{a} \times \vec{b} + \vec{b} \times \vec{c} + \vec{c} \times \vec{a}]$$

The points A, B & C are collinear if  $\vec{a} \times \vec{b} + \vec{b} \times \vec{c} + \vec{c} \times \vec{a} = \vec{0}$

☞ Area of any quadrilateral whose diagonal vectors are  $\vec{d}_1$  &  $\vec{d}_2$  is given by

$$\frac{1}{2} |\vec{d}_1 \times \vec{d}_2|$$

☞ Lagrange's Identity :  $(\vec{a} \times \vec{b})^2 = |\vec{a}|^2 |\vec{b}|^2 - (\vec{a} \cdot \vec{b})^2 = \begin{vmatrix} \vec{a} \cdot \vec{a} & \vec{a} \cdot \vec{b} \\ \vec{a} \cdot \vec{b} & \vec{b} \cdot \vec{b} \end{vmatrix}$

#### IV. **Scalar Triple Product:**

☞ The scalar triple product of three vectors  $\vec{a}$ ,  $\vec{b}$  &  $\vec{c}$  is defined as:

$$\vec{a} \times \vec{b} \cdot \vec{c} = |\vec{a}| |\vec{b}| |\vec{c}| \sin \theta \cos \phi$$

☞ Volume of tetrahedron  $V = \frac{1}{6} [\vec{a} \vec{b} \vec{c}]$

☞ In a scalar triple product the position of dot & cross can be interchanged i.e.

$$\vec{a} \cdot (\vec{b} \times \vec{c}) = (\vec{a} \times \vec{b}) \cdot \vec{c} \quad \text{OR} \quad [\vec{a} \ \vec{b} \ \vec{c}] = [\vec{b} \ \vec{c} \ \vec{a}] = [\vec{c} \ \vec{a} \ \vec{b}]$$

☞  $\vec{a} \cdot (\vec{b} \times \vec{c}) = -\vec{a} \cdot (\vec{c} \times \vec{b})$  i.e.  $[\vec{a} \ \vec{b} \ \vec{c}] = -[\vec{a} \ \vec{c} \ \vec{b}]$

☞ If  $\vec{a} = a_1\vec{i} + a_2\vec{j} + a_3\vec{k}$ ;  $\vec{b} = b_1\vec{i} + b_2\vec{j} + b_3\vec{k}$  &  $\vec{c} = c_1\vec{i} + c_2\vec{j} + c_3\vec{k}$  then  $[\vec{a} \vec{b} \vec{c}] = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$

☞ If  $\vec{a}$ ,  $\vec{b}$ ,  $\vec{c}$  are coplanar  $\Leftrightarrow [\vec{a} \vec{b} \vec{c}] = 0$ .

☞ Volume of tetrahedron OABC with O as origin & A( $\vec{a}$ ), B( $\vec{b}$ ) and C( $\vec{c}$ )

$$\text{be the vertices} = \left| \frac{1}{6} [\vec{a} \ \vec{b} \ \vec{c}] \right|$$

☞ The position vector of the centroid of a tetrahedron if the pv's of its vertices are  $\vec{a}$ ,  $\vec{b}$ ,  $\vec{c}$  &  $\vec{d}$  are given by  $\frac{1}{4} [\vec{a} + \vec{b} + \vec{c} + \vec{d}]$ .

#### V. **Vector Triple Product:**

$$\vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c})\vec{b} - (\vec{a} \cdot \vec{b})\vec{c}, \quad (\vec{a} \times \vec{b}) \times \vec{c} = (\vec{a} \cdot \vec{c})\vec{b} - (\vec{b} \cdot \vec{c})\vec{a}$$

☞  $(\vec{a} \times \vec{b}) \times \vec{c} \neq \vec{a} \times (\vec{b} \times \vec{c}),$  in general

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